 <b>Integrated Solutions Technology, Inc.</b>	<b>Title</b>  <b>IST3025 Specification</b>  160 Segment / Common STN Driver	文件編號 DOC#	版次 Rev
		IST-RD-0026	003
			生效日期 Effective Date : 2/06/2004

<h1>Specification</h1>			
Written by Department	Written by / Date	Approved by QRA Manager	Issued by D.C.C.
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文件變更履歷頁

Document Change History

版次 Rev.	變更項次 Change Items#	變更內容簡述 Change Description	變更依據文件號碼 ECN #	生效日期 Eff. Date
001	-	New Release	E01030005	1/30/2003
002	Page1~27	配合進入正式量產(3/06/2003)階段,刪除各首頁之 Preliminary 字樣	E03030004	3/07/2003
003	Page 23	Bump pad size change	E20040001	2/06/2004
接續頁 CONTINUATION --- <input checked="" type="checkbox"/> 是 YES; <input type="checkbox"/> 否 NO				

# IST3025 160-output LCD Segment/Common Driver IC

## DESCRIPTION

The IST3025 is a 160-output segment/common driver IC suitable for driving medium size dot matrix LCD panels. The IST3025 is good both segment driver and common driver, and suitable for a low power consuming, high-precision LCD.

## FEATURES

- Number of LCD drive outputs:160
- Supply voltage for the logic system:+2.5 to +5.5 V
- Supply voltage for LCD drive:+10.0 to +40.0 V
- Low power consumption
- Low output impedance
- Operating temperature:-30 to +85°C
- Package : TCP(Tape Carrier Package)/ Gold Bumped Chip

Bumped Chip

(Segment mode)

- Shift clock frequency : 8 MHz(MAX)
- 4-bit/8-bit parallel input modes are selectable with a mode(MD)pin

- Automatic transfer function of an enable signal
- Automatic counting function which, in the chip selection mode, causes the internal clock to be stopped by automatically counting 160 bits of input data

- Line latch circuits are reset when /DISPOFF active

(Common mode)

- Shift clock frequency : 4 MHz(MAX.)
- Built-in 160-bit bi-directional shift register (divisible into 80 bits x 2)
- Available in a single mode(160-bit shift register) or in a dual mode(80-bit shift register x 2)

(1)  $Y_1 \rightarrow Y_{160}$  Single mode

(2)  $Y_{160} \rightarrow Y_1$  Single mode

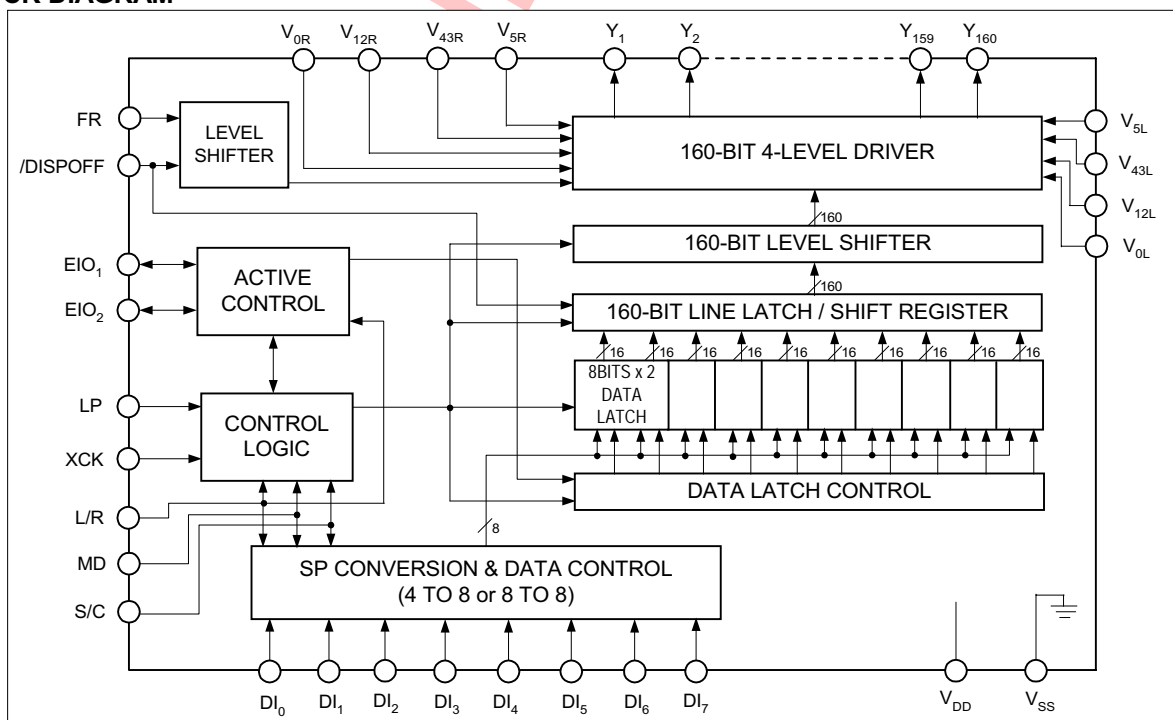
(3)  $Y_1 \rightarrow Y_{80}, Y_{81} \rightarrow Y_{160}$  Dual mode

(4)  $Y_{160} \rightarrow Y_{81}, Y_{80} \rightarrow Y_1$  Dual mode

The above 4 shift directions are pin-selectable

- Shift register circuits are reset when /DISPOFF active

## BLOCK DIAGRAM





FUNCTIONAL OPERATIONS OF EACH BLOCK

BLOCK	FUNCTION
Active Control	In case of segment mode, controls the selection or non-selection of chip. Following an LP signal input, and after the chip selection signal is input, a selection signal is generated internally until 160 bits of data have been read in. Once data input has been completed, a selection signal for cascade connection is output, and the chip is non-selected. In case of common mode, controls the input/output data of bi-directional pins.
SP Conversion & Data Control	In case of segment mode, keeps input data which are 2 clocks of XCK at 4-bit parallel Input mode in latch circuit, or keeps input data which are 1 clock of XCK at 8-bit parallel Input mode in latch circuit; after that they are put on the internal data bus 8 bits at a time.
Data Latch Control	In case of segment mode, selects the state of the data latch which reads in the data bus signals. The shift direction is controlled by the control logic. For every 16 bits of data read in, the selection signal shifts one bit based on the state of the control circuit.
Data Latch	In case of segment mode, latches the data on the data bus. The latch state of each LCD drive output pin is controlled by the control logic and the data latch control; 160 bits of data are read in 20 sets of 8 bits.
Line Latch/ Shift Register	In case of segment mode, all 160 bits which have been read into the data latch are simultaneously latched at the falling edge of the LP signal, and are output to the level shifter block. In case of common mode, shifts data from the data input pin at the falling edge of the LP signal.
Level Shifter	The logic voltage signal is level-shifted to the LCD drive voltage level, and is output to the driver block.
4-Level Driver	Drives the LCD drive output pins from the line latch/shift register data, and selects one of 4 levels ( $V_0, V_{12}, V_{43},$ or $V_5$ ) based on the S/C, FR and /DISPOFF signals.
Control Logic	Controls the operation of each block. In case of segment mode, when an LP signal has been input, all blocks are reset and the control logic waits for the selection signal output from the active control block. Once the selection signal has been output, operation of the data latch and data transmission is controlled, 160 bits of data are read in, and the chip is non-selected. In case of common mode, controls the direction of data shift.



**PIN DESCRIPTION**

SYMBOL	I/O	DESCRIPTION
$Y_1 \rightarrow Y_{160}$	O	LCD drive output
$V_{0L}, V_{0R}$	-	Power supply for LCD drive
$V_{12L}, V_{12R}$	-	Power supply for LCD drive
$V_{43L}, V_{43R}$	-	Power supply for LCD drive
$V_{5L}, V_{5R}$	-	Power supply for LCD drive
L/R	I	Input for selecting the reading direction of display data at segment mode/ Input for selecting the shift direction of shift register at common mode
$V_{DD}$	-	Power supply for logic system (+2.5 to +5.5 V)
S/C	I	Segment mode/common mode selection
$EIO_2, EIO_1$	I/O	Input/output for chip selection at segment mode/ Shift data input/output for shift register at common mode
$DI_0-DI_6$	I	Display data input at segment mode
$DI_7$	I	Display data input at segment mode/Dual mode data input at common mode
XCK	I	Clock input for taking display data at segment mode
/DISPOFF	I	Control input for output of non-select level
LP	I	Latch pulse input for display data at segment mode/ Shift clock input for shift register at common mode
FR	I	AC-converting signal input for LCD drive waveform
MD	I	Mode selection input
$V_{SS}$	-	Ground (0 V)

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**FUNCTIONAL DESCRIPTION**
**Pin Functions**

(Segment mode)

<b>SYMBOL</b>	<b>FUNCTION</b>
$V_{DD}$	Logic system power supply pin, connected to +2.5 to +5.5 V.
$V_{SS}$	Ground pin, connected to 0 V.
$V_{0L}, V_{0R}$ $V_{12L}, V_{12R}$ $V_{43L}, V_{43R}$ $V_{5L}, V_{5R}$	Bias power supply pins for LCD drive voltage <ul style="list-style-type: none"> <li>• Normally use the bias voltages set by a resistor divider</li> <li>• Ensure that voltages are set such that <math>V_{SS} \leq V_5 &lt; V_{43} &lt; V_{12} &lt; V_0</math>.</li> </ul>
$DI_7-DI_0$	Input pins for display data <ul style="list-style-type: none"> <li>• In 4-bit parallel input mode, input data into the 4 pins, <math>DI_3-DI_0</math>. Connect <math>DI_7-DI_4</math> to <math>V_{SS}</math> or <math>V_{DD}</math>.</li> <li>• In 8-bit parallel input mode, input data into the 8 pins, <math>DI_7-DI_0</math>.</li> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
XCK	Clock input pin for taking display data <ul style="list-style-type: none"> <li>• Data is read at the falling edge of the clock pulse.</li> </ul>
LP	Latch pulse input pin for display data <ul style="list-style-type: none"> <li>• Data is latched at the falling edge of the clock pulse.</li> </ul>
L/R	Input pin for selecting the reading direction of display data <ul style="list-style-type: none"> <li>• When set to <math>V_{SS}</math> level "L", data is read sequentially from <math>Y_{160}</math> to <math>Y_1</math>.</li> <li>• When set to <math>V_{DD}</math> level "H", data is read sequentially from <math>Y_1</math> to <math>Y_{160}</math>.</li> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
/DISPOFF	Control input pin for output of non-select level <ul style="list-style-type: none"> <li>• The input signal is level-shifted from logic voltage level to LCD drive voltage level, and controls the LCD drive circuit.</li> <li>• When set to <math>V_{SS}</math> level "L", the LCD drive output pins (<math>Y_1-Y_{160}</math>) are set to level <math>V_5</math>.</li> <li>• When set to "L", the contents of the line latch are reset, but the display data are read in the data latch regardless of the condition of /DISPOFF. When the /DISPOFF function is canceled, the driver outputs non-select level (<math>V_{12}</math> or <math>V_{43}</math>), then outputs the contents of the data latch at the next falling edge of the LP. At that time, if /DISPOFF removal time does not correspond to what is shown in AC characteristics, it can not output the reading data correctly.</li> <li>• Table of truth values is shown in "<b>TRUTH TABLE</b>" in Functional Operations.</li> </ul>



(Segment mode continuous)

SYMBOL	FUNCTION
FR	<p>AC signal input pin for LCD drive waveform</p> <ul style="list-style-type: none"> <li>• The input signal is level-shifted from logic voltage level to LCD drive voltage level, and controls the LCD drive circuit.</li> <li>• Normally it inputs a frame inversion signal.</li> <li>• The LCD drive output pins' output voltage levels can be set using the line latch output signal and the FR signal.</li> <li>• Table of truth values is shown in "<b>TRUTH TABLE</b>" in Functional Operations.</li> </ul>
MD	<p>Mode selection pin</p> <ul style="list-style-type: none"> <li>• When set to <math>V_{SS}</math> level "L", 4-bit parallel input mode is set.</li> <li>• When set to <math>V_{DD}</math> level "H", 8-bit parallel input mode is set.</li> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
S/C	<p>Segment mode/common mode selection pin</p> <ul style="list-style-type: none"> <li>• When set to <math>V_{DD}</math> level "H", segment mode is set.</li> </ul>
EIO <sub>1</sub> -EIO <sub>2</sub>	<p>Input/output pins for chip selection</p> <ul style="list-style-type: none"> <li>• When L/R input is at <math>V_{SS}</math> level "L", EIO<sub>1</sub> is set for output, and EIO<sub>2</sub> is set for input.</li> <li>• When L/R input is at <math>V_{DD}</math> level "H", EIO<sub>1</sub> is set for input, and EIO<sub>2</sub> is set for output.</li> <li>• During output, set to "H" while LP • /XCK is "H" and after 160 bits of data have been read, set to "L" for one cycle (from falling edge to falling edge of XCK), after which it returns to "H".</li> <li>• During input, the chip is selected while EI is set to "L" after the LP signal is input. The chip is non-selected after 160 bits of data have been read. (EI : When EIO<sub>1</sub>,EIO<sub>2</sub> is set for input ; EO : When EIO<sub>1</sub>,EIO<sub>2</sub> is set for output.)</li> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
Y <sub>1</sub> -Y <sub>160</sub>	<p>LCD drive output pins</p> <ul style="list-style-type: none"> <li>• Corresponding directly to each bit of the data latch, one level (<math>V_0</math>, <math>V_{12}</math>, <math>V_{43}</math>, or <math>V_5</math>) is selected and output.</li> <li>• Table of truth values is shown in "<b>TRUTH TABLE</b>" in Functional Operations.</li> </ul>



(Common mode)

SYMBOL	FUNCTION
$V_{DD}$	Logic system power supply pin, connected to +2.5 to +5.5 V.
$V_{SS}$	Ground pin, connected to 0 V.
$V_{0L}, V_{0R}$ $V_{12L}, V_{12R}$ $V_{43L}, V_{43R}$ $V_{5L}, V_{5R}$	<p>Bias power supply pins for LCD drive voltage</p> <ul style="list-style-type: none"> <li>• Normally use the bias voltages set by a resistor divider</li> <li>• Ensure that voltages are set such that <math>V_{SS} \leq V_5 &lt; V_{43} &lt; V_{12} &lt; V_0</math>.</li> </ul>
$EIO_1$	<p>Shift data input/output pin for bi-directional shift register</p> <ul style="list-style-type: none"> <li>• Output pin when L/R is at <math>V_{SS}</math> level "L", input pin when L/R is at <math>V_{DD}</math> level "H".</li> <li>• When L/R = H, <math>EIO_1</math> is used as input pin, it will be pulled down.</li> <li>• When L/R = L, <math>EIO_1</math> is used as output pin, it won't be pulled down.</li> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
$EIO_2$	<p>Shift data input/output pin for bi-directional shift register</p> <ul style="list-style-type: none"> <li>• Input pin when L/R is at <math>V_{SS}</math> level "L", output pin when L/R is at <math>V_{DD}</math> level "H".</li> <li>• When L/R = L, <math>EIO_2</math> is used as input pin, it will be pulled down.</li> <li>• When L/R = H, <math>EIO_2</math> is used as output pin, it won't be pulled down.</li> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
LP	<p>Shift clock pulse input pin for bi-directional shift register</p> <ul style="list-style-type: none"> <li>• Data is shifted at the falling edge of the clock pulse.</li> </ul>
L/R	<p>Input pin for selecting the shift direction of bi-directional shift register</p> <ul style="list-style-type: none"> <li>• Data is shifted from <math>Y_{160}</math> to <math>Y_1</math> when set to <math>V_{SS}</math> level "L", and data is shifted from <math>Y_1</math> to <math>Y_{160}</math> when set to <math>V_{DD}</math> level "H".</li> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
/DISPOFF	<p>Control input pin for output of non-select level</p> <ul style="list-style-type: none"> <li>• The input signal is level-shifted from logic voltage level to LCD drive voltage level, and controls the LCD drive circuit.</li> <li>• When set to <math>V_{SS}</math> level "L", the LCD drive output pins (<math>Y_1</math>-<math>Y_{160}</math>) are set to level <math>V_5</math>.</li> <li>• When set to "L", the contents of the shift register are reset to not reading data. When the /DISPOFF function is canceled, the driver outputs non-select level (<math>V_{12}</math> or <math>V_{43}</math>), and the shift data is read at the next falling edge of the LP. At that time, if /DISPOFF removal time does not correspond to what is shown in AC characteristics, the data is not read correctly.</li> <li>• Table of truth values is shown in "<b>TRUTH TABLE</b>" in Functional Operations.</li> </ul>





(Common mode continuous)

SYMBOL	FUNCTION
FR	<p>AC signal input pin for LCD drive waveform</p> <ul style="list-style-type: none"> <li>• The input signal is level-shifted from logic voltage level to LCD drive voltage level, and controls the LCD drive circuit.</li> <li>• Normally it inputs a frame inversion signal.</li> <li>• The LCD drive output pins' output voltage levels can be set using the line latch output signal and the FR signal.</li> <li>• Table of truth values is shown in "<b>TRUTH TABLE</b>" in Functional Operations.</li> </ul>
MD	<p>Mode selection pin</p> <ul style="list-style-type: none"> <li>• When set to <math>V_{SS}</math> level "L", single mode is selected; when set to <math>V_{DD}</math> level "H", dual mode is selected</li> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
DI <sub>7</sub>	<p>Dual mode data input pin</p> <ul style="list-style-type: none"> <li>• According to the data shift direction of the data shift register, data can be input starting from the 81st bit.</li> </ul> <p>When the chip is used in dual mode, DI<sub>7</sub> will be pulled down.</p> <p>When the chip is used in single mode, DI<sub>7</sub> won't be pulled down.</p> <ul style="list-style-type: none"> <li>• Refer to "<b>RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS</b>" in Functional Operations.</li> </ul>
S/C	<p>Segment mode/common mode selection pin</p> <ul style="list-style-type: none"> <li>• When set to <math>V_{SS}</math> level "L", common mode is set.</li> </ul>
DI <sub>6</sub> -DI <sub>0</sub>	<p>Not used</p> <ul style="list-style-type: none"> <li>• Connect DI<sub>6</sub>-DI<sub>0</sub> to <math>V_{SS}</math> or <math>V_{DD}</math>, avoiding floating.</li> </ul>
XCK	<p>Not used</p> <ul style="list-style-type: none"> <li>• XCK is pulled down in common mode, so connect to <math>V_{SS}</math> or open.</li> </ul>
Y <sub>1</sub> -Y <sub>160</sub>	<p>LCD drive output pins</p> <ul style="list-style-type: none"> <li>• Corresponding directly to each bit of the shift register, one level (<math>V_0</math>, <math>V_{12}</math>, <math>V_{43}</math>, or <math>V_5</math>) is selected and output.</li> <li>• Table of truth values is shown in "<b>TRUTH TABLE</b>" in Functional Operations.</li> </ul>



Functional Operations

TRUTH TABLE

(Segment Mode)

FR	LATCH DATA	/DISPOFF	LCD DRIVE OUTPUT VOLTAGE LEVEL (Y <sub>1</sub> -Y <sub>160</sub> )
L	L	H	V <sub>43</sub>
L	H	H	V <sub>5</sub>
H	L	H	V <sub>12</sub>
H	H	H	V <sub>0</sub>
X	X	L	V <sub>5</sub>

(Common Mode)

FR	LATCH DATA	/DISPOFF	LCD DRIVE OUTPUT VOLTAGE LEVEL (Y <sub>1</sub> -Y <sub>160</sub> )
L	L	H	V <sub>43</sub>
L	H	H	V <sub>0</sub>
H	L	H	V <sub>12</sub>
H	H	H	V <sub>5</sub>
X	X	L	V <sub>5</sub>

NOTES :

- $V_{SS} \leq V_5 < V_{43} < V_{12} < V_0$ , L : V<sub>SS</sub> (0 V), H : V<sub>DD</sub> (+2.5 to +5.5 V), X : Don't care
- "Don't care" should be fixed to "H" or "L", avoiding floating.

There are two kinds of power supply (logic level voltage and LCD drive voltage) for the LCD driver.

Supply regular voltage which is assigned by specification for each power pin.

**RELATIONSHIP BETWEEN THE DISPLAY DATA AND LCD DRIVE OUTPUT PINS**

(Segment Mode)

(a) 4-bit Parallel Input Mode

MD	L/R	EIO <sub>1</sub>	EIO <sub>2</sub>	DATA INPUT	NUMBER OF CLOCKS						
					40 CLOCK	39 CLOCK	38 CLOCK	...	3 CLOCK	2 CLOCK	1 CLOCK
L	L	Output	Input	DI <sub>0</sub>	Y <sub>1</sub>	Y <sub>5</sub>	Y <sub>9</sub>	...	Y <sub>149</sub>	Y <sub>153</sub>	Y <sub>157</sub>
				DI <sub>1</sub>	Y <sub>2</sub>	Y <sub>6</sub>	Y <sub>10</sub>	...	Y <sub>150</sub>	Y <sub>154</sub>	Y <sub>158</sub>
				DI <sub>2</sub>	Y <sub>3</sub>	Y <sub>7</sub>	Y <sub>11</sub>	...	Y <sub>151</sub>	Y <sub>155</sub>	Y <sub>159</sub>
				DI <sub>3</sub>	Y <sub>4</sub>	Y <sub>8</sub>	Y <sub>12</sub>	...	Y <sub>152</sub>	Y <sub>156</sub>	Y <sub>160</sub>
L	H	Input	Output	DI <sub>0</sub>	Y <sub>160</sub>	Y <sub>156</sub>	Y <sub>152</sub>	...	Y <sub>12</sub>	Y <sub>8</sub>	Y <sub>4</sub>
				DI <sub>1</sub>	Y <sub>159</sub>	Y <sub>155</sub>	Y <sub>151</sub>	...	Y <sub>11</sub>	Y <sub>7</sub>	Y <sub>3</sub>
				DI <sub>2</sub>	Y <sub>158</sub>	Y <sub>154</sub>	Y <sub>150</sub>	...	Y <sub>10</sub>	Y <sub>6</sub>	Y <sub>2</sub>
				DI <sub>3</sub>	Y <sub>157</sub>	Y <sub>153</sub>	Y <sub>149</sub>	...	Y <sub>9</sub>	Y <sub>5</sub>	Y <sub>1</sub>

(b) 8-bit Parallel Input Mode

MD	L/R	EIO <sub>1</sub>	EIO <sub>2</sub>	DATA INPUT	NUMBER OF CLOCKS						
					20 CLOCK	19 CLOCK	18 CLOCK	...	3 CLOCK	2 CLOCK	1 CLOCK
H	L	Output	Input	DI <sub>0</sub>	Y <sub>1</sub>	Y <sub>9</sub>	Y <sub>17</sub>	...	Y <sub>137</sub>	Y <sub>145</sub>	Y <sub>153</sub>
				DI <sub>1</sub>	Y <sub>2</sub>	Y <sub>10</sub>	Y <sub>18</sub>	...	Y <sub>138</sub>	Y <sub>146</sub>	Y <sub>154</sub>
				DI <sub>2</sub>	Y <sub>3</sub>	Y <sub>11</sub>	Y <sub>19</sub>	...	Y <sub>139</sub>	Y <sub>147</sub>	Y <sub>155</sub>
				DI <sub>3</sub>	Y <sub>4</sub>	Y <sub>12</sub>	Y <sub>20</sub>	...	Y <sub>140</sub>	Y <sub>148</sub>	Y <sub>156</sub>
				DI <sub>4</sub>	Y <sub>5</sub>	Y <sub>13</sub>	Y <sub>21</sub>	...	Y <sub>141</sub>	Y <sub>149</sub>	Y <sub>157</sub>
				DI <sub>5</sub>	Y <sub>6</sub>	Y <sub>14</sub>	Y <sub>22</sub>	...	Y <sub>142</sub>	Y <sub>150</sub>	Y <sub>158</sub>
				DI <sub>6</sub>	Y <sub>7</sub>	Y <sub>15</sub>	Y <sub>23</sub>	...	Y <sub>143</sub>	Y <sub>151</sub>	Y <sub>159</sub>
				DI <sub>7</sub>	Y <sub>8</sub>	Y <sub>16</sub>	Y <sub>24</sub>	...	Y <sub>144</sub>	Y <sub>152</sub>	Y <sub>160</sub>
H	H	Input	Output	DI <sub>0</sub>	Y <sub>160</sub>	Y <sub>152</sub>	Y <sub>144</sub>	...	Y <sub>24</sub>	Y <sub>16</sub>	Y <sub>8</sub>
				DI <sub>1</sub>	Y <sub>159</sub>	Y <sub>151</sub>	Y <sub>143</sub>	...	Y <sub>23</sub>	Y <sub>15</sub>	Y <sub>7</sub>
				DI <sub>2</sub>	Y <sub>158</sub>	Y <sub>150</sub>	Y <sub>142</sub>	...	Y <sub>22</sub>	Y <sub>14</sub>	Y <sub>6</sub>
				DI <sub>3</sub>	Y <sub>157</sub>	Y <sub>149</sub>	Y <sub>141</sub>	...	Y <sub>21</sub>	Y <sub>13</sub>	Y <sub>5</sub>
				DI <sub>4</sub>	Y <sub>156</sub>	Y <sub>148</sub>	Y <sub>140</sub>	...	Y <sub>20</sub>	Y <sub>12</sub>	Y <sub>4</sub>
				DI <sub>5</sub>	Y <sub>155</sub>	Y <sub>147</sub>	Y <sub>139</sub>	...	Y <sub>19</sub>	Y <sub>11</sub>	Y <sub>3</sub>
				DI <sub>6</sub>	Y <sub>154</sub>	Y <sub>146</sub>	Y <sub>138</sub>	...	Y <sub>18</sub>	Y <sub>10</sub>	Y <sub>2</sub>
				DI <sub>7</sub>	Y <sub>153</sub>	Y <sub>145</sub>	Y <sub>137</sub>	...	Y <sub>17</sub>	Y <sub>9</sub>	Y <sub>1</sub>

(Common Mode)

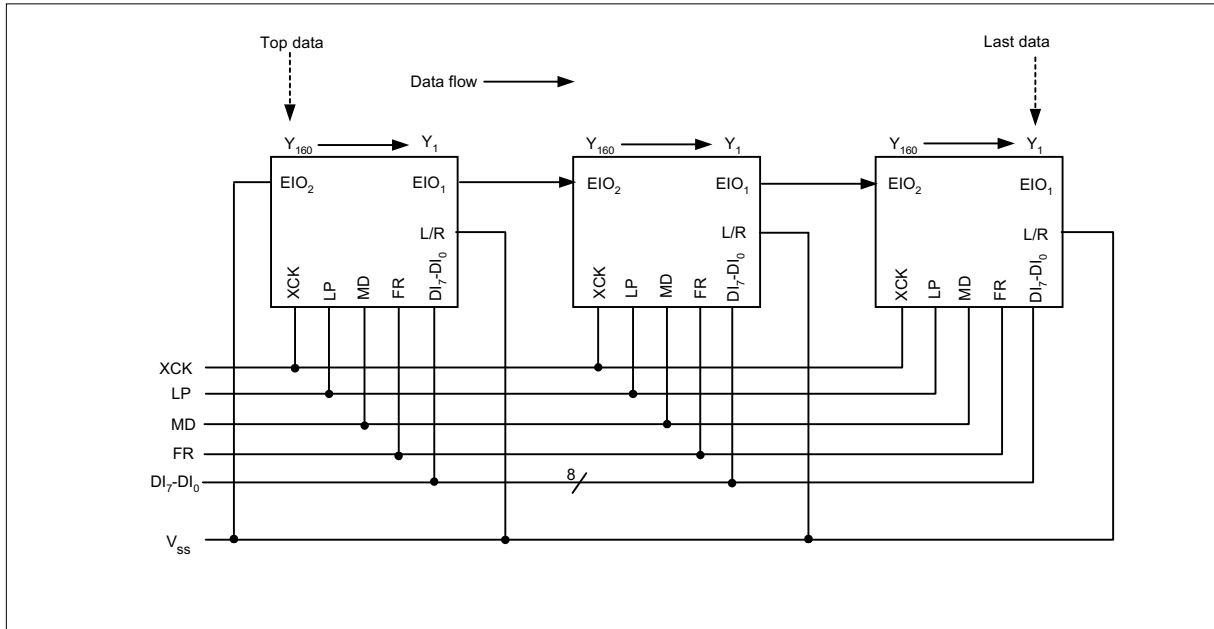
MD	L/R	DATA TRANSFER DIRECTION	EIO <sub>1</sub>	EIO <sub>2</sub>	DI <sub>7</sub>
L (Single)	L	Y <sub>160</sub> → Y <sub>1</sub>	Output	Input	X
	H	Y <sub>1</sub> → Y <sub>160</sub>	Input	Output	X
H (Dual)	L	Y <sub>160</sub> → Y <sub>81</sub> Y <sub>80</sub> → Y <sub>1</sub>	Output	Input	Input
	H	Y <sub>1</sub> → Y <sub>80</sub> Y <sub>81</sub> → Y <sub>160</sub>	Input	Output	Input

**NOTES :**

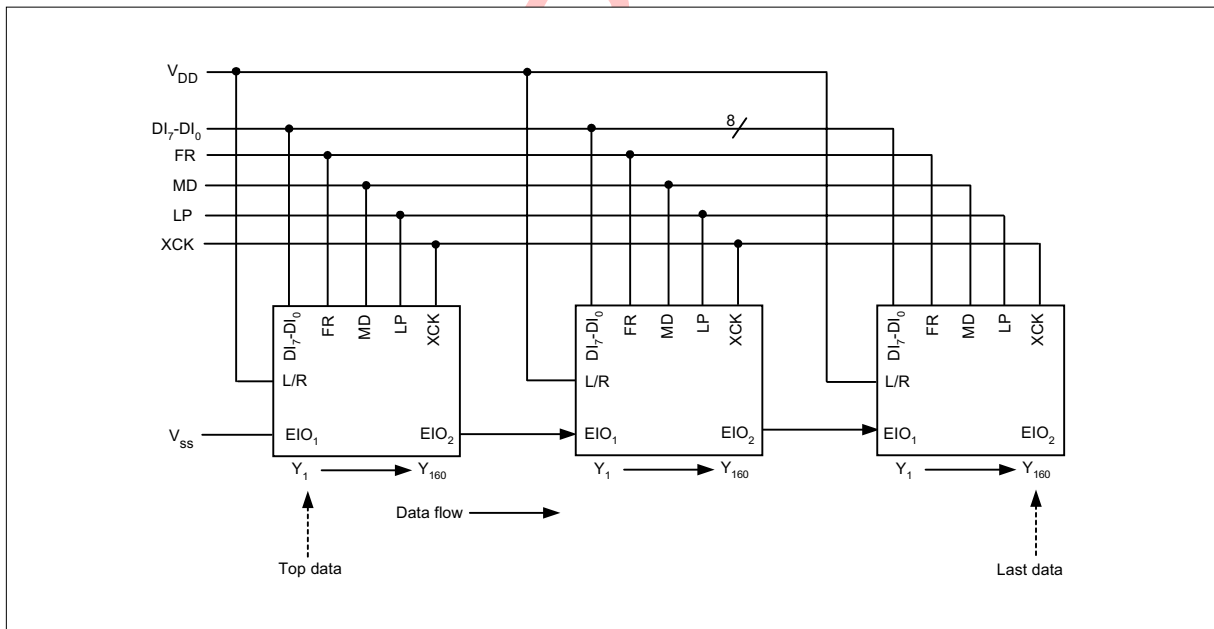
- L : V<sub>SS</sub> (0 V), H : V<sub>DD</sub> (+2.5 to +5.5 V), X : Don't care
- "Don't care" should be fixed to "H" or "L", avoiding floating.

**CONNECTION EXAMPLES OF PLURAL SEGMENT DRIVERS**

**(a)When L/R= "L"**

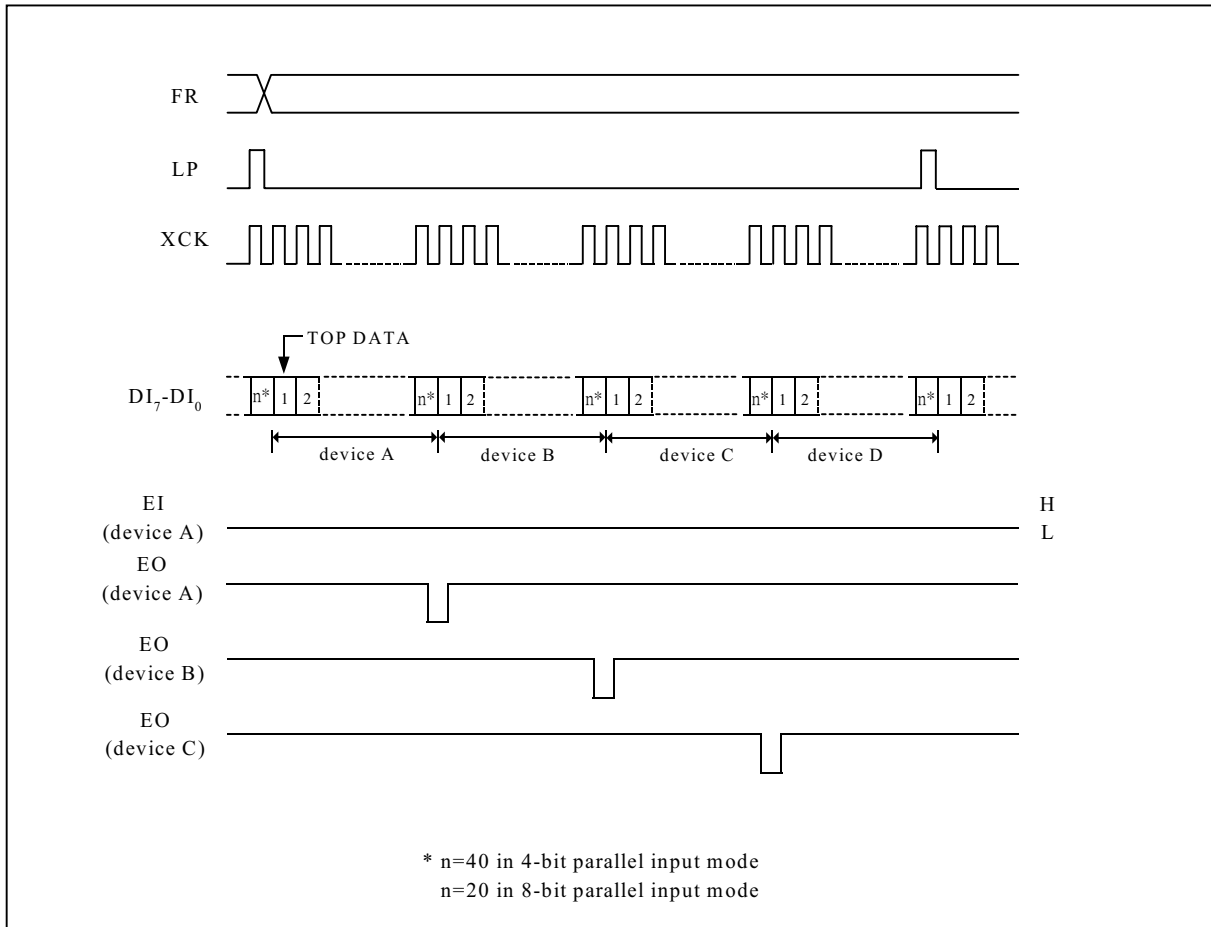


**(b)When L/R= "H"**





TIMING CHART OF 4-DEVICE CASCADE CONNECTION OF SEGMENT DRIVERS

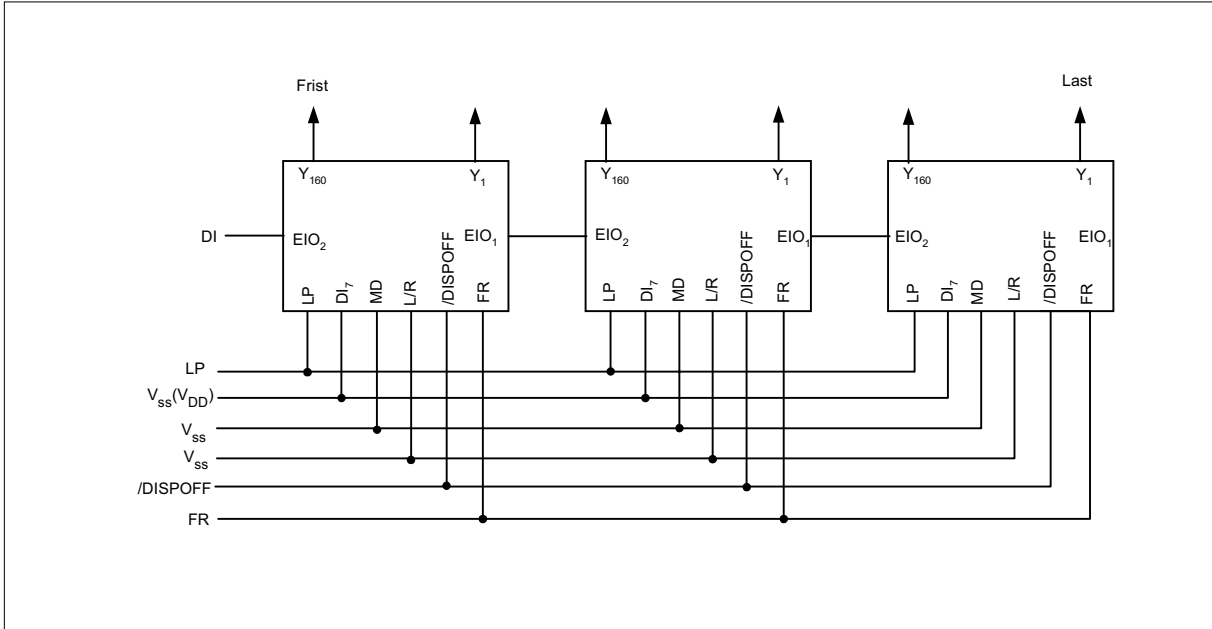


CONF

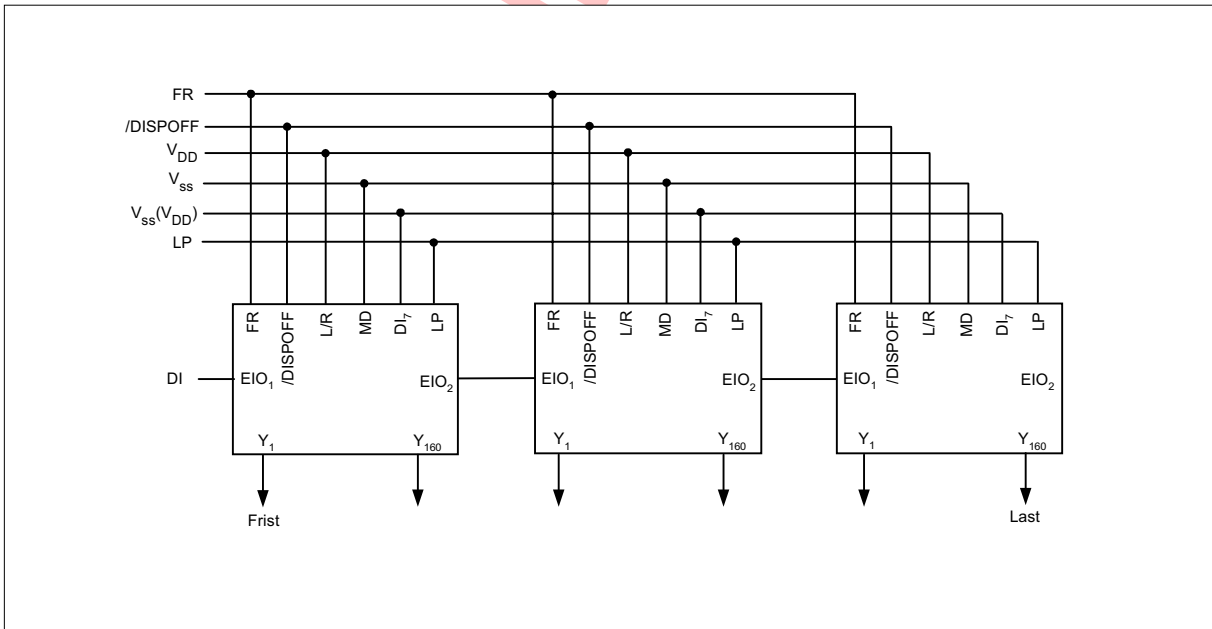


CONNECTION EXAMPLES FOR PLURAL COMMON DRIVERS

(a) Single Mode (L/R= "L")

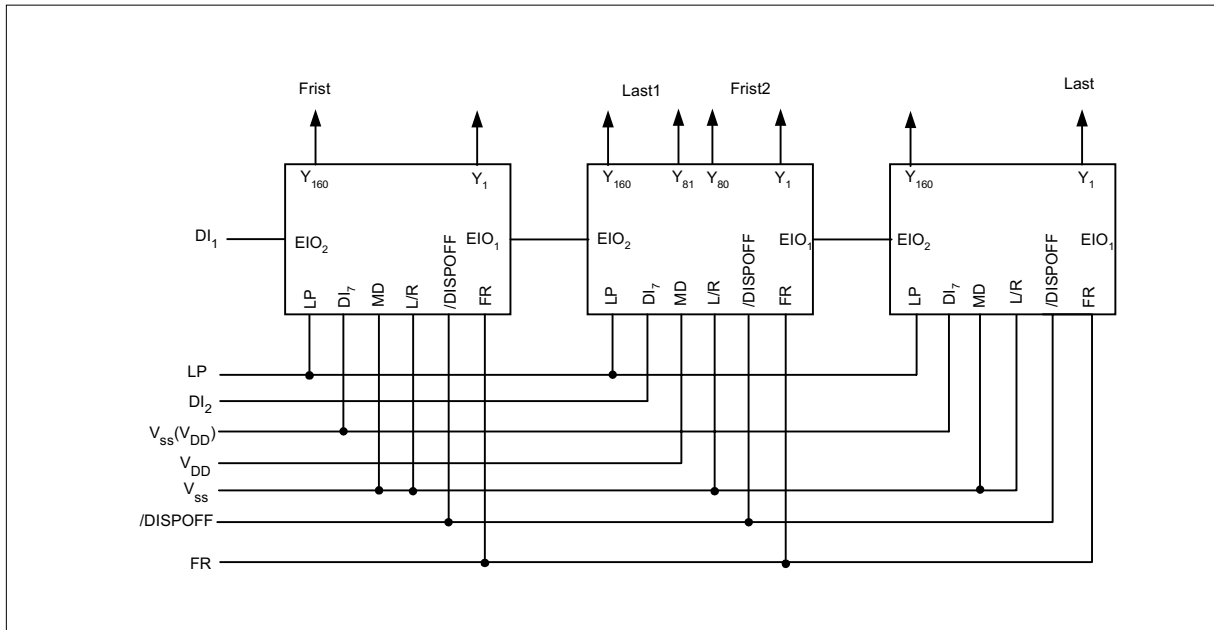


(b) Single Mode (L/R= "H")

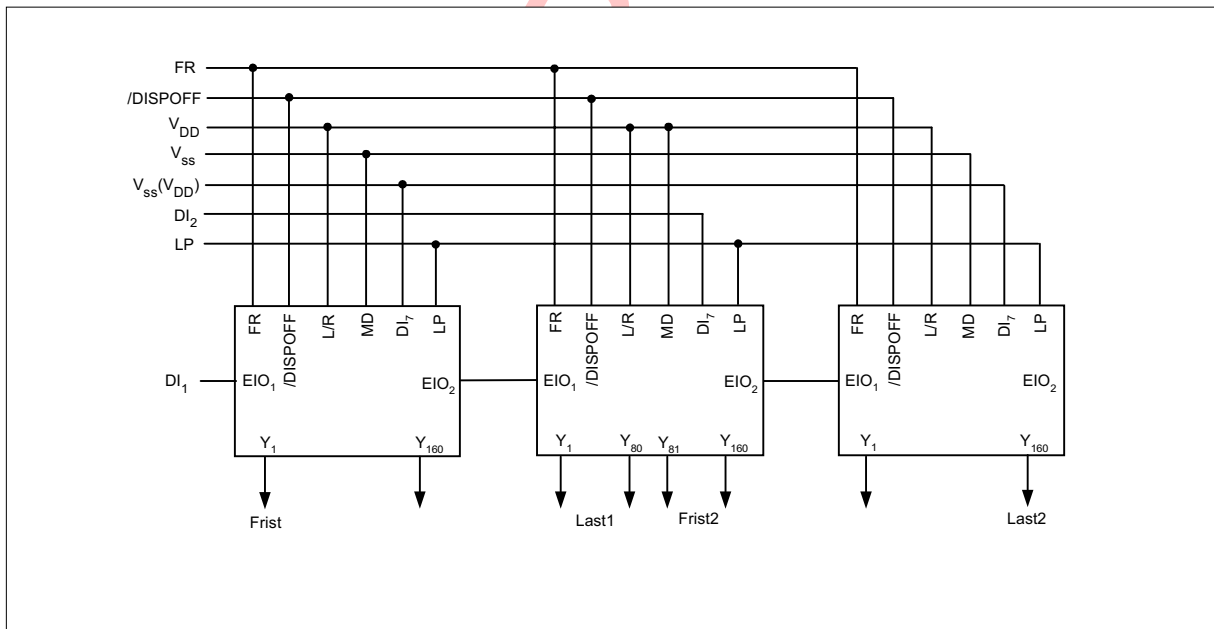




(c) Dual Mode (L/R= "L")



(d) Dual Mode (L/R= "H")





**ABSOLUTE MAXIMUM RATINGS**

PARAMETER	SYMBOL	APPLICABLE PINS	RATING	UNIT	NOTE
Supply voltage (1)	V <sub>DD</sub>	V <sub>DD</sub>	-0.3 to +7.0	V	1,2
Supply voltage (2)	V <sub>0</sub>	V <sub>0L</sub> , V <sub>0R</sub>	-0.3 to +40.0	V	
	V <sub>12</sub>	V <sub>12L</sub> , V <sub>12R</sub>	-0.3 to V <sub>0</sub> +0.3	V	
	V <sub>43</sub>	V <sub>43L</sub> , V <sub>43R</sub>	-0.3 to V <sub>0</sub> +0.3	V	
	V <sub>5</sub>	V <sub>5L</sub> , V <sub>5R</sub>	-0.3 to V <sub>0</sub> +0.3	V	
Input voltage	V <sub>I</sub>	DI <sub>0</sub> -DI <sub>7</sub> , XCL, LP, FR, MD, S/C, EIO <sub>1</sub> , EIO <sub>2</sub> , /DISPOFF	-0.3 to V <sub>DD</sub> +0.3	V	
Storage temperature	T <sub>STG</sub>		-45 to +125	°C	

**NOTES :**

1. TA= +25 °C
2. The maximum applicable voltage on any pin with respect to V<sub>SS</sub> (0 V).

**RECOMMENDED OPERATING CONDITIONS**

PARAMETER	SYMBOL	APPLICABLE PINS	MIN.	TYP.	MAX.	UNIT	NOTE
Supply voltage (1)	V <sub>DD</sub>	V <sub>DD</sub>	+2.5		+5.5	V	1,2
Supply voltage (2)	V <sub>0</sub>	V <sub>0L</sub> , V <sub>0R</sub>	+10.0		+40.0	V	
Operating temperature	T <sub>OPR</sub>		-30		+85	°C	

**NOTES :**

1. The applicable voltage on any pin with respect to V<sub>SS</sub> (0 V).
2. Ensure that voltages are set such that V<sub>SS</sub> ≤ V<sub>5</sub> < V<sub>43</sub> < V<sub>12</sub> < V<sub>0</sub>.



**ELECTRICAL CHARACTERISTICS**
**DC Characteristics**

 (Segment Mode) ( $V_{SS} = V_5 = 0\text{ V}$ ,  $V_{DD} = +2.5\text{ to }+5.5\text{ V}$ ,  $V_0 = +10.0\text{ to }+40.0\text{ V}$ ,  $T_{OPR} = -30\text{ to }+85\text{ }^\circ\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	APPLICABLE PINS	MIN.	TYP.	MAX.	UNIT	NOTE
Input "Low" voltage	$V_{IL}$		DI <sub>7</sub> -DI <sub>0</sub> , XCK, LP, L/R,			0.2V <sub>DD</sub>	V	
Input "High" voltage	$V_{IH}$		FR, MD, S/C, EIO <sub>1</sub> , EIO <sub>2</sub> , /DISPOFF	0.8V <sub>DD</sub>			V	
Output "Low" voltage	$V_{OL}$	I <sub>OL</sub> =+0.4 mA	EIO <sub>1</sub> , EIO <sub>2</sub>			+0.4	V	
Output "High" voltage	$V_{OH}$	I <sub>OH</sub> =-0.4 mA		V <sub>DD</sub> -0.4				V
Input leakage current	$I_{LIL}$	$V_I = V_{SS}$	DI <sub>7</sub> -DI <sub>0</sub> , XCK, LP, L/R,			-10.0	μA	
	$I_{LIH}$	$V_I = V_{DD}$	FR, MD, S/C, EIO <sub>1</sub> , EIO <sub>2</sub> , /DISPOFF			+10.0	μA	
Output resistance	$R_{ON}$	ΔV <sub>ON</sub>   =0.5V	Y <sub>1</sub> -Y <sub>160</sub>		1.0	1.5	KΩ	
				V <sub>0</sub> =30V V <sub>0</sub> =20V		1.5		
Standby current	$I_{STB}$		V <sub>SS</sub>			50.0	μA	1
Supply current (1) (Non-selection)	$I_{DD1}$		V <sub>DD</sub>			2.0	mA	2
Supply current (2) (selection)	$I_{DD2}$		V <sub>DD</sub>			7.0	mA	3
Supply current (3)	$I_0$		V <sub>0L</sub> , V <sub>0R</sub>			0.9	mA	4

**NOTES :**

- $V_{DD} = +5.0\text{ V}$ ,  $V_0 = +30.0\text{ V}$ ,  $V_{IH} = V_{DD}$ ,  $V_{IL} = V_{SS}$ .
- $V_{DD} = +5.0\text{ V}$ ,  $V_0 = +30.0\text{ V}$ ,  $f_{XCK} = 8\text{ MHz}$ , no-load,  
EI = V<sub>DD</sub>.  
The input data is turned over by data taking clock  
(4-bit parallel input mode).
- $V_{DD} = +5.0\text{ V}$ ,  $V_0 = +30.0\text{ V}$ ,  $f_{XCK} = 8\text{ MHz}$ , no-load,  
EI = V<sub>SS</sub>.  
The input data is turned over by data taking clock  
(4-bit parallel input mode).
- $V_{DD} = +5.0\text{ V}$ ,  $V_0 = +30.0\text{ V}$ ,  $f_{XCK} = 8\text{ MHz}$ ,  
 $f_{LP} = 19.2\text{ kHz}$ ,  $f_{FR} = 80\text{ Hz}$ , no-load.  
The input data is turned over by data taking clock  
(4-bit parallel input mode).



(Common Mode) ( $V_{SS} = V_5 = 0\text{ V}$ ,  $V_{DD} = +2.5\text{ to }+5.5\text{ V}$ ,  $V_0 = +10.0\text{ to }+40.0\text{ V}$ ,  $T_{OPR} = -30\text{ to }+85\text{ }^\circ\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	APPLICABLE PINS	MIN.	TYP.	MAX.	UNIT	NOTE
Input "Low" voltage	$V_{IL}$		DI <sub>7</sub> -DI <sub>0</sub> , XCK, LP, L/R, FR, MD, S/C, EIO <sub>1</sub> ,			0.2V <sub>DD</sub>	V	
Input "High" voltage	$V_{IH}$		EIO <sub>2</sub> , /DISPOFF	0.8V <sub>DD</sub>			V	
Output "Low" voltage	$V_{OL}$	I <sub>OL</sub> =+0.4 mA	EIO <sub>1</sub> , EIO <sub>2</sub>			+0.4	V	
Output "High" voltage	$V_{OH}$	I <sub>OH</sub> =-0.4 mA		V <sub>DD</sub> -0.4			V	
Input leakage current	$I_{LIL}$	$V_1 = V_{SS}$	DI <sub>7</sub> -DI <sub>0</sub> , XCK, LP, L/R, FR, MD, S/C, EIO <sub>1</sub> , EIO <sub>2</sub> , /DISPOFF			-10.0	μA	
	$I_{LIH}$	$V_1 = V_{DD}$	DI <sub>6</sub> -DI <sub>0</sub> , LP, L/R, FR, MD, S/C, /DISPOFF			+10.0	μA	
Input pull-down current	$I_{PD}$	$V_1 = V_{DD}$	DI <sub>7</sub> , XCK, EIO <sub>1</sub> , EIO <sub>2</sub>			100.0	μA	3
						200.0	μA	4
Output resistance	$R_{ON}$	ΔV <sub>ON</sub>   =0.5V	Y <sub>1</sub> -Y <sub>160</sub>		1.0	1.5	KΩ	
				$V_0=30\text{V}$	1.5	2.0		
Standby current	$I_{STB}$		$V_{SS}$			50.0	μA	1
Supply current (1)	$I_{DD}$		$V_{DD}$			80.0	μA	2
Supply current (2)	$I_0$		$V_{OL}$ , $V_{OR}$			130.0	μA	2

**NOTES :**

- $V_{DD} = +5.0\text{ V}$ ,  $V_0 = +30.0\text{ V}$ ,  $V_1 = V_{SS}$
- $V_{DD} = +5.0\text{ V}$ ,  $V_0 = +30.0\text{ V}$ ,  $f_{LP} = 19.2\text{ kHz}$ ,  $f_{FR} = 80\text{ Hz}$ , 1/240 duty operation, no-load.
- $V_{DD} = +2.5\text{ to }+3.3\text{ V}$
- $V_{DD} = +3.3\text{ to }+5.5\text{ V}$



**AC Characteristics**

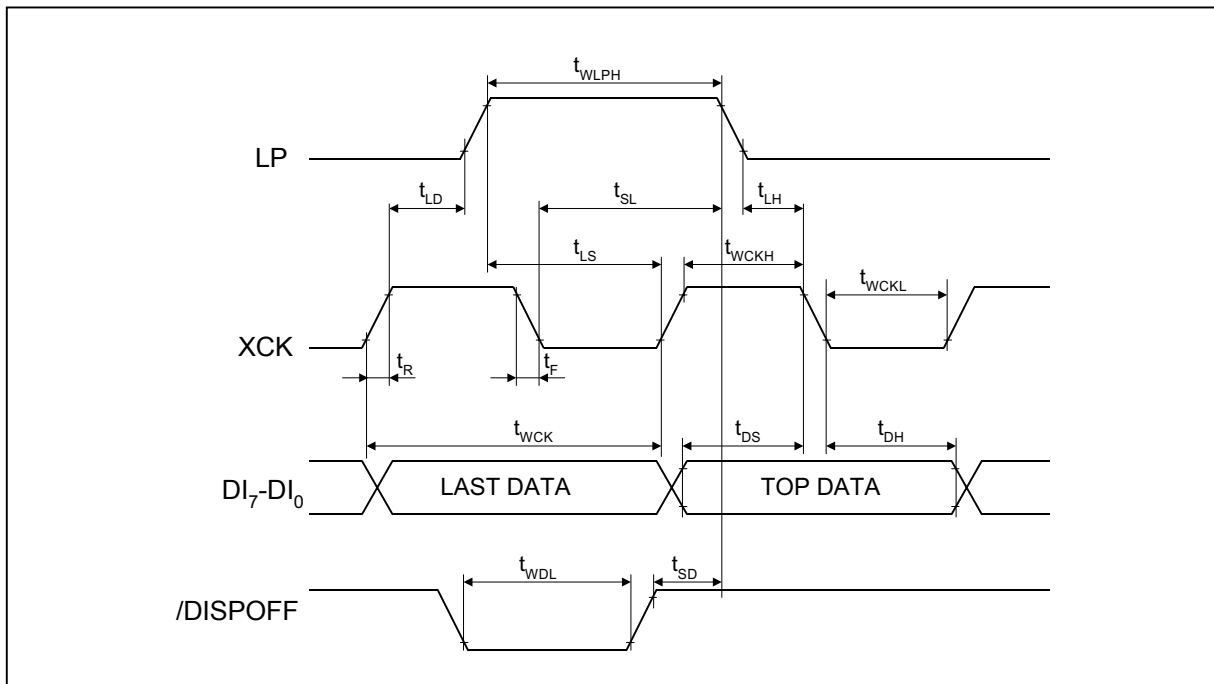
(Segment Mode) ( $V_{SS} = V_5 = 0\text{ V}$ ,  $V_{DD} = +2.5\text{ to }+5.5\text{ V}$ ,  $V_0 = +10.0\text{ to }+40.0\text{ V}$ ,  $T_{OPR} = -30\text{ to }+85\text{ }^\circ\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNIT	NOTE
Shift clock period	$t_{WCK}$	$t_R, t_F \leq 11\text{ ns}$	125			ns	1
Shift clock "H" pulse width	$t_{WCKH}$		51			ns	
Shift clock "L" pulse width	$t_{WCKL}$		51			ns	
Data setup time	$t_{DS}$		30			ns	
Data hold time	$t_{DH}$		40			ns	
Latch pulse "H" pulse width	$t_{WLPH}$		51			ns	
Shift clock rise to latch pulse rise time	$t_{LD}$		0			ns	
Shift clock fall to latch pulse fall time	$t_{SL}$		51			ns	
Latch pulse rise to shift clock rise time	$t_{LS}$		51			ns	
Latch pulse fall to shift clock fall time	$t_{LH}$		51			ns	
Enable setup time	$t_S$		36			ns	
Input signal rise time	$t_R$				50	ns	2
Input signal fall time	$t_F$				50	ns	2
/DISPOFF removal time	$t_{SD}$		100			ns	
/DISPOFF "L" pulse width	$t_{WDL}$		1.2			$\mu\text{s}$	
Output delay time (1)	$t_D$	$C_L = 15\text{ pF}$			78	ns	
Output delay time (2)	$t_{PD1}, t_{PD2}$	$C_L = 15\text{ pF}$			1.2	$\mu\text{s}$	
Output delay time (3)	$t_{PD3}$	$C_L = 15\text{ pF}$			1.2	$\mu\text{s}$	

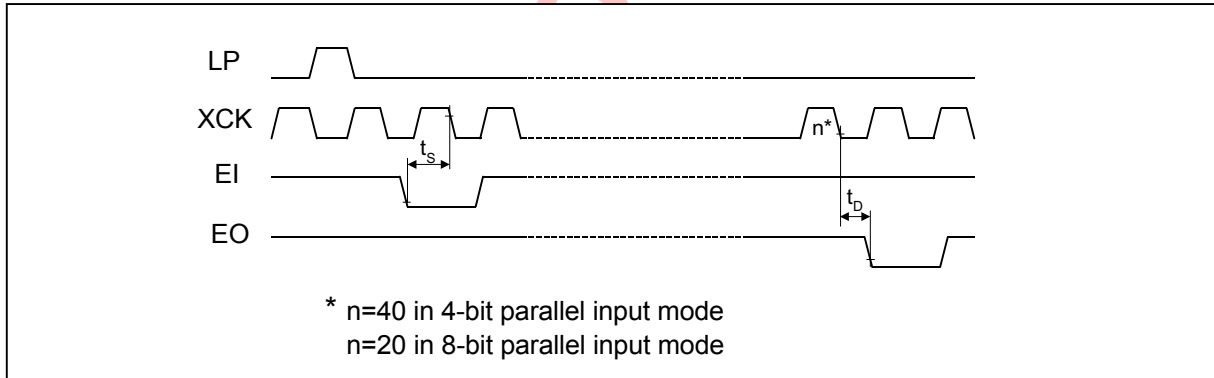
**NOTES :**

1. Takes the cascade connection into consideration.
2.  $(t_{WCK} - t_{WCKH} - t_{WCKL})/2$  is maximum in the case of high speed operation.

**Timing Chart of Segment Mode**



**Fig.6 Timing Characteristics (1)**



**Fig.7 Timing Characteristics (2)**

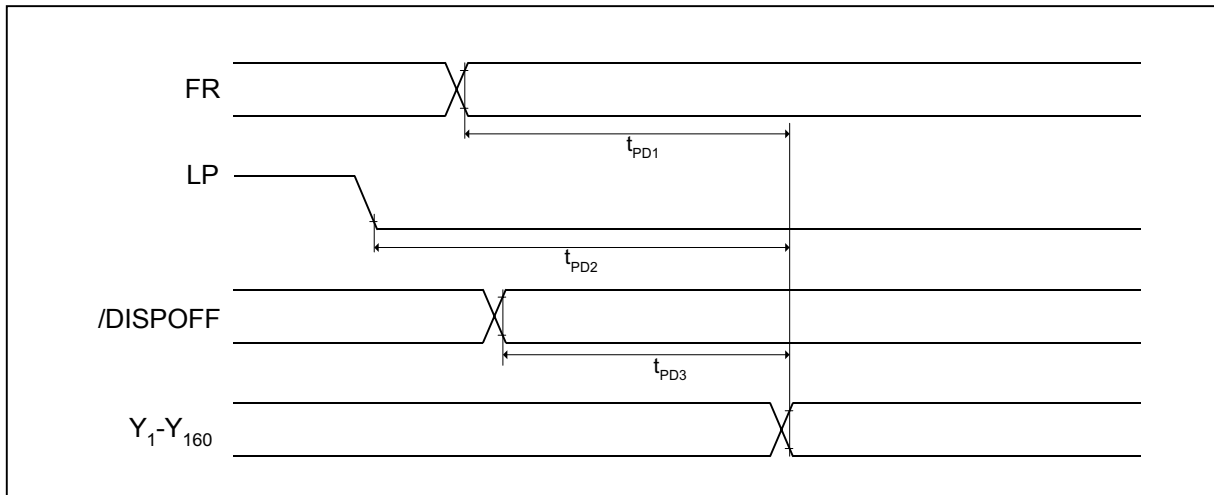


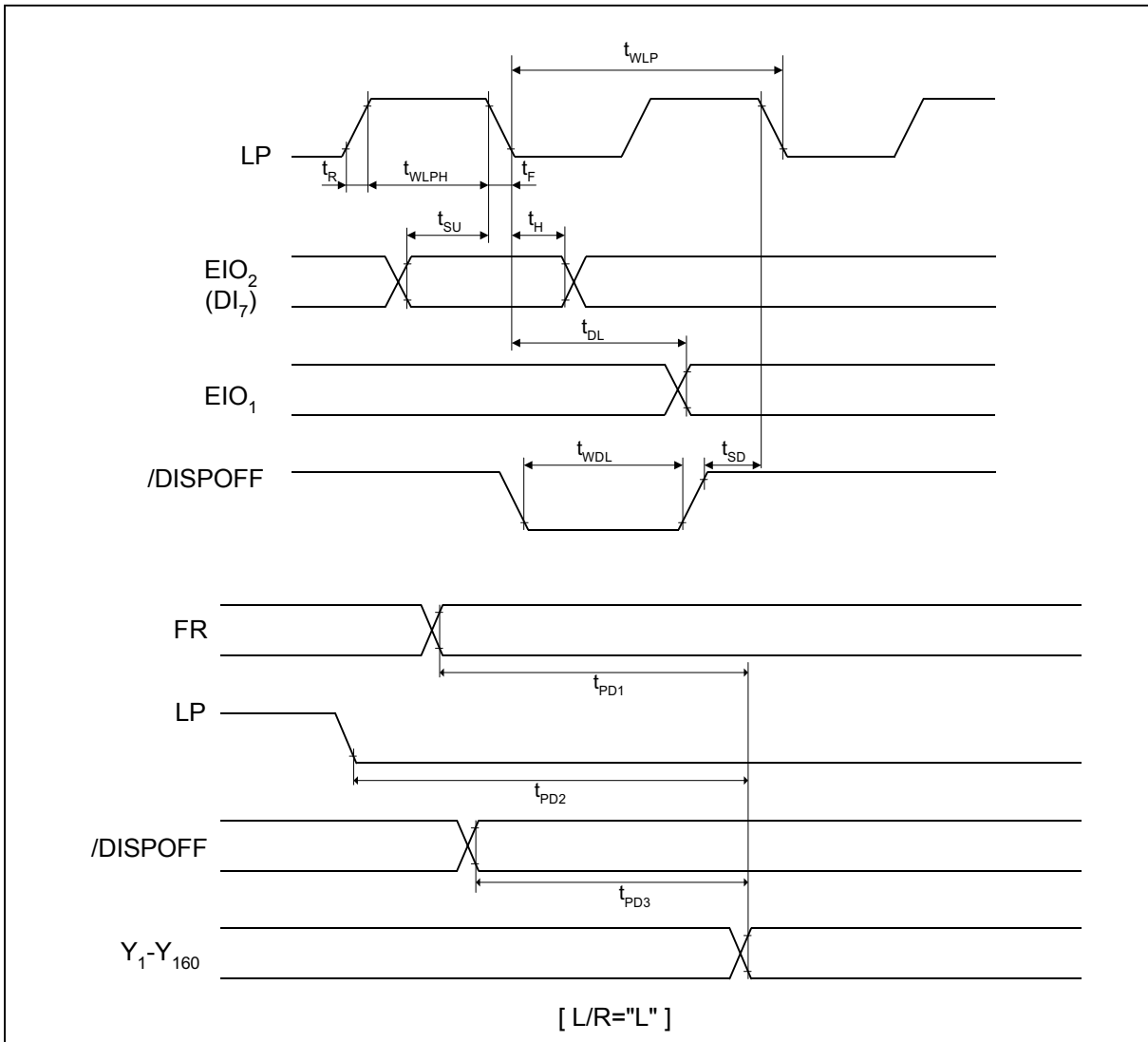
Fig.8 Timing Characteristics(3)

(Common Mode) ( $V_{SS} = V_5 = 0\text{ V}$ ,  $V_{DD} = +2.5\text{ to }+5.5\text{ V}$ ,  $V_0 = +10.0\text{ to }+40\text{ V}$ ,  $T_{OPR} = -30\text{ to }+85\text{ }^\circ\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Shift clock period	$t_{WLP}$	$t_R, t_F \leq 20\text{ ns}$	250			ns
Shift clock "H" pulse width	$t_{WLPH}$	$V_{DD} = +5.0 \pm 0.5\text{V}$	15			ns
		$V_{DD} = +2.5\text{ to }+4.5\text{V}$	30			ns
Data setup time	$t_{SU}$		30			ns
Data hold time	$t_H$		50			ns
Input signal rise time	$t_R$				50	ns
Input signal fall time	$t_F$				50	ns
/DISPOFF removal time	$t_{SD}$		100			ns
/DISPOFF "L" pulse width	$T_{WDL}$		1.2			$\mu\text{s}$
Output delay time (1)	$t_{DL}$	$C_L = 15\text{ pF}$			200	ns
Output delay time (2)	$t_{PD1}, t_{PD2}$	$C_L = 15\text{ pF}$			1.2	$\mu\text{s}$
Output delay time (3)	$t_{PD3}$	$C_L = 15\text{ pF}$			1.2	$\mu\text{s}$

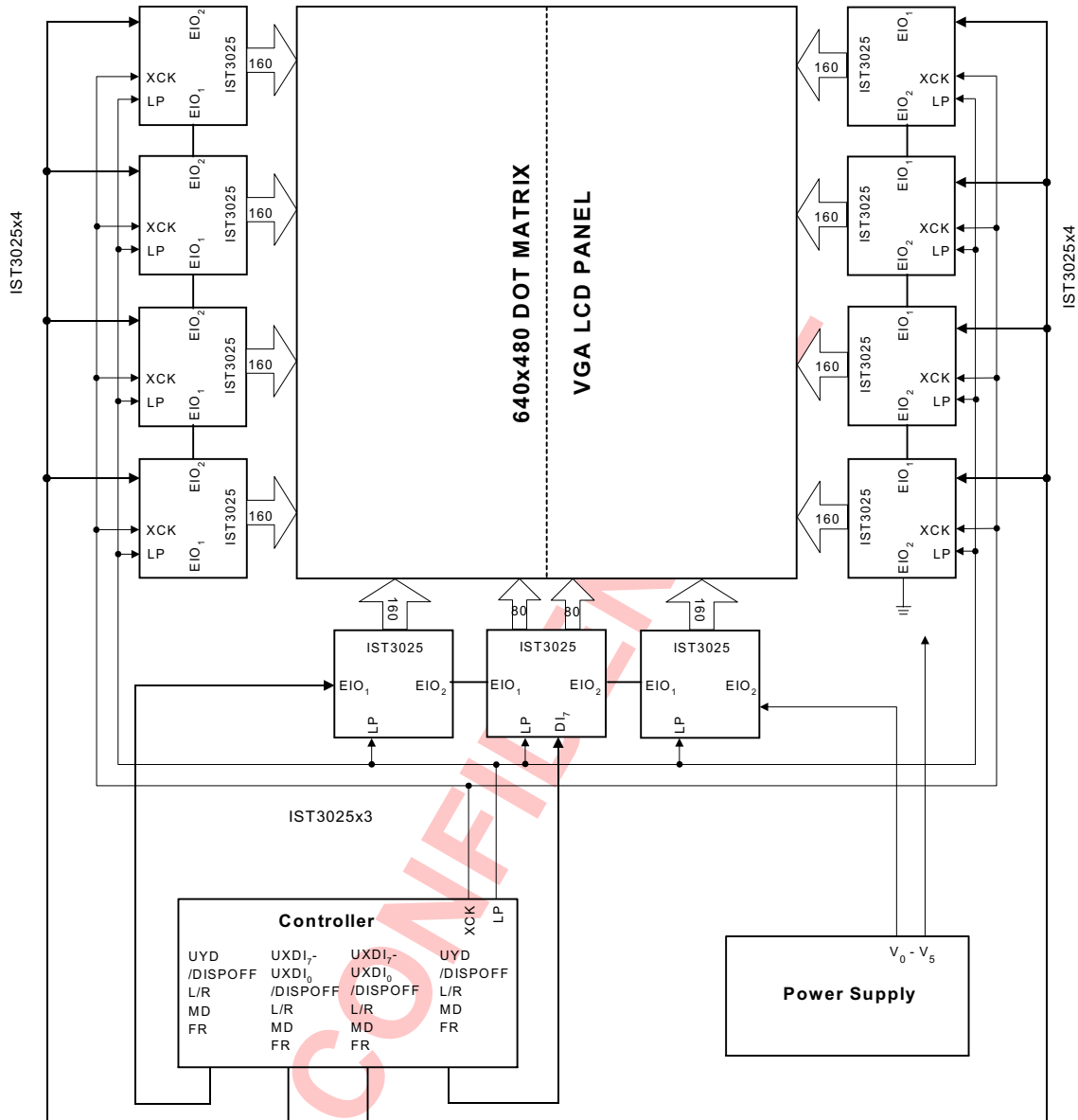


Timing Chart of Common Mode





SYSTEM CONFIGURATION EXAMPLE





**PRECAUTIONS**

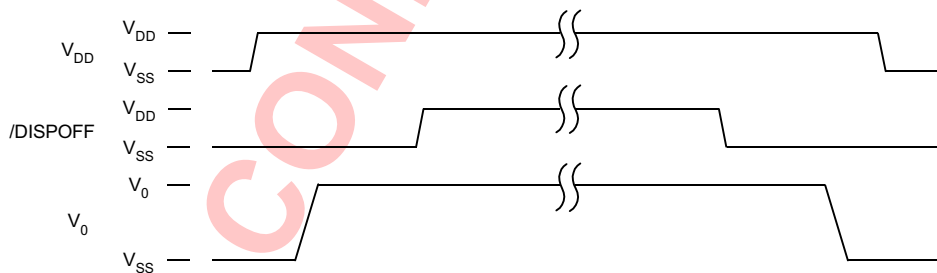
**Precautions when connecting or disconnecting the power supply**

This IC has a high-voltage LCD driver, so it may be permanently damaged by a high current which may flow if voltage is supplied to the LCD drive power supply while the logic system power supply is floating. The details are as follows.

- When connecting the power supply, connect the LCD drive power after connecting the logic system power. Furthermore, when disconnecting the power, disconnect the logic system power after disconnecting the LCD drive power.
- It is advisable to connect the serial resistor (50 to 100  $\Omega$  ) or fuse to the LCD drive power  $V_0$  of the system as a current limiter. Set up a suitable value of the resistor in consideration of the display grade.

And when connecting the logic power supply, the logic condition of this IC inside is insecure. Therefore connect the LCD drive power supply after resetting logic condition of this IC inside on /DISPOFF function. After that, cancel the /DISPOFF function after the LCD drive power supply has become stable. Furthermore, when disconnecting the power, set the LCD drive output pins to level  $V_5$  on /DISPOFF function. Then, disconnect the logic system power after disconnecting the LCD drive power.

When connecting the power supply, follow the recommended sequence shown here.







PAD CONFIGURATION :

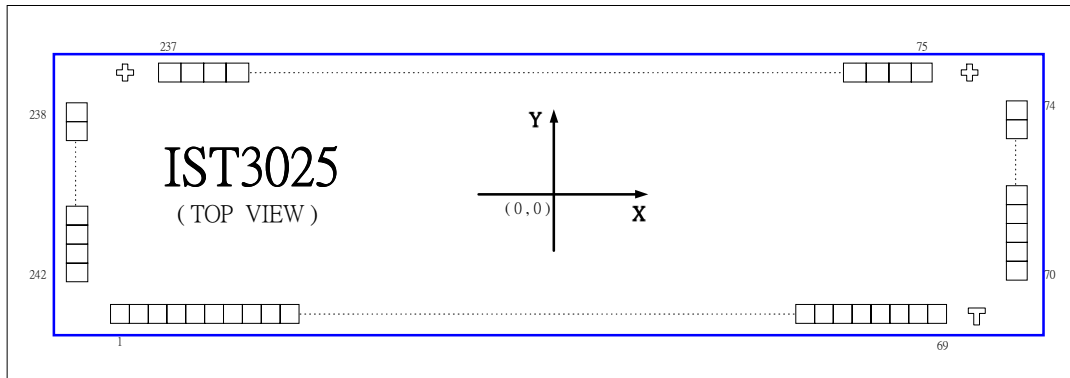


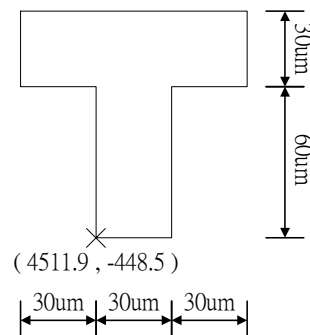
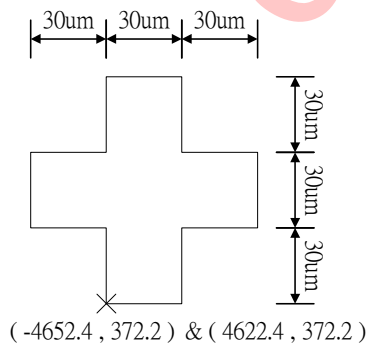
Figure 1 : IST3025 Chip Configuration

Table 1. IST3025 Pad Dimensions

※Note: All dummy pads have gold bumps.

Item	Pad No.	Size		Unit
		X	Y	
Chip size	242	9540	1080	um
Pad pitch	1 to 74, 238 to 242	100 (min)		
	75 to 237	55 (min)		
Bumped pad size	1 to 3, 64 to 69,	61	85	
	75,237	61	83	
	4 to 18, 58 to 63,	37	85	
	76 to 236	37	83	
	19 to 57	79	37	
	70 to 74, 238 to 242	85	61	
Bumped pad height	All pad	18		

COG Align Key Coordinate





PAD CENTER COORDINATES :

Table 2 : Pad Center Coordinates

Unit : um

PAD NO.	PAD NAME	PAD COORDINATES		PAD NO.	PAD NAME	PAD COORDINATES	
		X	Y			X	Y
1	DUMMY	-4446.8	-406.2	36	DUMMY	321.9	-426.2
2	V5	-4296.4	-406.2	37	DUMMY	421.9	-426.2
3	VSS	-4072.4	-406.2	38	DUMMY	521.9	-426.2
4	L/R	-3903.2	-406.2	39	DUMMY	621.9	-426.2
5	VDD	-3711.2	-406.2	40	DUMMY	721.9	-426.2
6	SC	-3589.4	-406.2	41	DUMMY	821.9	-426.2
7	VSS	-3407.4	-406.2	42	DUMMY	921.9	-426.2
8	EIO2	-3285.6	-406.2	43	DUMMY	1021.9	-426.2
9	DI0	-3089.9	-406.2	44	DUMMY	1121.9	-426.2
10	DI1	-2925.3	-406.2	45	DUMMY	1221.9	-426.2
11	DI2	-2729.1	-406.2	46	DUMMY	1321.9	-426.2
12	DI3	-2564.5	-406.2	47	DUMMY	1421.9	-426.2
13	VSS	-2382.5	-406.2	48	DUMMY	1521.9	-426.2
14	DI4	-2260.7	-406.2	49	DUMMY	1621.9	-426.2
15	DI5	-2064.5	-406.2	50	DUMMY	1721.9	-426.2
16	DI6	-1899.9	-406.2	51	DUMMY	1821.9	-426.2
17	DI7	-1703.7	-406.2	52	DUMMY	1921.9	-426.2
18	XCK	-1539.1	-406.2	53	DUMMY	2021.9	-426.2
19	DUMMY	-1378.1	-426.2	54	DUMMY	2121.9	-426.2
20	DUMMY	-1278.1	-426.2	55	DUMMY	2221.9	-426.2
21	DUMMY	-1178.1	-426.2	56	DUMMY	2321.9	-426.2
22	DUMMY	-1078.1	-426.2	57	DUMMY	2421.9	-426.2
23	DUMMY	-978.1	-426.2	58	/DISPOFF	2578.5	-406.2
24	DUMMY	-878.1	-426.2	59	LP	2743.1	-406.2
25	DUMMY	-778.1	-426.2	60	EIO1	2938.8	-406.2
26	DUMMY	-678.1	-426.2	61	FR	3103.4	-406.2
27	DUMMY	-578.1	-426.2	62	VDD	3295.4	-406.2
28	DUMMY	-478.1	-426.2	63	MD	3417.2	-406.2
29	DUMMY	-378.1	-426.2	64	VSS	3566.8	-406.2
30	DUMMY	-278.1	-426.2	65	VSS	3758.6	-406.2
31	DUMMY	-178.1	-426.2	66	VSS	3873.4	-406.2
32	DUMMY	-78.1	-426.2	67	VSS	4104.2	-406.2
33	DUMMY	21.9	-426.2	68	V5	4268.0	-406.2
34	DUMMY	121.9	-426.2	69	DUMMY	4418.4	-406.2
35	DUMMY	221.9	-426.2	70	DUMMY	4640.0	-338.4



**Table 2 : Pad Center Coordinates ( Continued )**

**Unit : um**

<b>PAD NO.</b>	<b>PAD NAME</b>	<b>PAD COORDINATES</b>		<b>PAD NO.</b>	<b>PAD NAME</b>	<b>PAD COORDINATES</b>	
		<b>X</b>	<b>Y</b>			<b>X</b>	<b>Y</b>
71	V43	4640.0	-180.4	106	Y31	2777.5	420.0
72	V12	4640.0	24.0	107	Y32	2722.5	420.0
73	V0	4640.0	241.2	108	Y33	2667.5	420.0
74	DUMMY	4640.0	325.2	109	Y34	2612.5	420.0
75	DUMMY	4499.5	420.0	110	Y35	2557.5	420.0
76	Y1	4427.5	420.0	111	Y36	2502.5	420.0
77	Y2	4372.5	420.0	112	Y37	2447.5	420.0
78	Y3	4317.5	420.0	113	Y38	2392.5	420.0
79	Y4	4262.5	420.0	114	Y39	2337.5	420.0
80	Y5	4207.5	420.0	115	Y40	2282.5	420.0
81	Y6	4152.5	420.0	116	Y41	2227.5	420.0
82	Y7	4097.5	420.0	117	Y42	2172.5	420.0
83	Y8	4042.5	420.0	118	Y43	2117.5	420.0
84	Y9	3987.5	420.0	119	Y44	2062.5	420.0
85	Y10	3932.5	420.0	120	Y45	2007.5	420.0
86	Y11	3877.5	420.0	121	Y46	1952.5	420.0
87	Y12	3822.5	420.0	122	Y47	1897.5	420.0
88	Y13	3767.5	420.0	123	Y48	1842.5	420.0
89	Y14	3712.5	420.0	124	Y49	1787.5	420.0
90	Y15	3657.5	420.0	125	Y50	1732.5	420.0
91	Y16	3602.5	420.0	126	Y51	1677.5	420.0
92	Y17	3547.5	420.0	127	Y52	1622.5	420.0
93	Y18	3492.5	420.0	128	Y53	1567.5	420.0
94	Y19	3437.5	420.0	129	Y54	1512.5	420.0
95	Y20	3382.5	420.0	130	Y55	1457.5	420.0
96	Y21	3327.5	420.0	131	Y56	1402.5	420.0
97	Y22	3272.5	420.0	132	Y57	1347.5	420.0
98	Y23	3217.5	420.0	133	Y58	1292.5	420.0
99	Y24	3162.5	420.0	134	Y59	1237.5	420.0
100	Y25	3107.5	420.0	135	Y60	1182.5	420.0
101	Y26	3052.5	420.0	136	Y61	1127.5	420.0
102	Y27	2997.5	420.0	137	Y62	1072.5	420.0
103	Y28	2942.5	420.0	138	Y63	1017.5	420.0
104	Y29	2887.5	420.0	139	Y64	962.5	420.0
105	Y30	2832.5	420.0	140	Y65	907.5	420.0



**Table 2 : Pad Center Coordinates ( Continued )**

**Unit : um**

<b>PAD NO.</b>	<b>PAD NAME</b>	<b>PAD COORDINATES</b>		<b>PAD NO.</b>	<b>PAD NAME</b>	<b>PAD COORDINATES</b>	
		<b>X</b>	<b>Y</b>			<b>X</b>	<b>Y</b>
141	Y66	852.5	420.0	176	Y100	-1127.5	420.0
142	Y67	797.5	420.0	177	Y101	-1182.5	420.0
143	Y68	742.5	420.0	178	Y102	-1237.5	420.0
144	Y69	687.5	420.0	179	Y103	-1292.5	420.0
145	Y70	632.5	420.0	180	Y104	-1347.5	420.0
146	Y71	577.5	420.0	181	Y105	-1402.5	420.0
147	Y72	522.5	420.0	182	Y106	-1457.5	420.0
148	Y73	467.5	420.0	183	Y107	-1512.5	420.0
149	Y74	412.5	420.0	184	Y108	-1567.5	420.0
150	Y75	357.5	420.0	185	Y109	-1622.5	420.0
151	Y76	302.5	420.0	186	Y110	-1677.5	420.0
152	Y77	247.5	420.0	187	Y111	-1732.5	420.0
153	Y78	192.5	420.0	188	Y112	-1787.5	420.0
154	Y79	137.5	420.0	189	Y113	-1842.5	420.0
155	Y80	82.5	420.0	190	Y114	-1897.5	420.0
156	DUMMY	0.0	420.0	191	Y115	-1952.5	420.0
157	Y81	-82.5	420.0	192	Y116	-2007.5	420.0
158	Y82	-137.5	420.0	193	Y117	-2062.5	420.0
159	Y83	-192.5	420.0	194	Y118	-2117.5	420.0
160	Y84	-247.5	420.0	195	Y119	-2172.5	420.0
161	Y85	-302.5	420.0	196	Y120	-2227.5	420.0
162	Y86	-357.5	420.0	197	Y121	-2282.5	420.0
163	Y87	-412.5	420.0	198	Y122	-2337.5	420.0
164	Y88	-467.5	420.0	199	Y123	-2392.5	420.0
165	Y89	-522.5	420.0	200	Y124	-2447.5	420.0
166	Y90	-577.5	420.0	201	Y125	-2502.5	420.0
167	Y91	-632.5	420.0	202	Y126	-2557.5	420.0
168	Y92	-687.5	420.0	203	Y127	-2612.5	420.0
169	Y93	-742.5	420.0	204	Y128	-2667.5	420.0
170	Y94	-797.5	420.0	205	Y129	-2722.5	420.0
171	Y95	-852.5	420.0	206	Y130	-2777.5	420.0
172	Y96	-907.5	420.0	207	Y131	-2832.5	420.0
173	Y97	-962.5	420.0	208	Y132	-2887.5	420.0
174	Y98	-1017.5	420.0	209	Y133	-2942.5	420.0
175	Y99	-1072.5	420.0	210	Y134	-2997.5	420.0



Table 2 : Pad Center Coordinates ( Continued )

Unit : um

PAD NO.	PAD NAME	PAD COORDINATES		PAD NO.	PAD NAME	PAD COORDINATES	
		X	Y			X	Y
211	Y135	-3052.5	420.0				
212	Y136	-3107.5	420.0				
213	Y137	-3162.5	420.0				
214	Y138	-3217.5	420.0				
215	Y139	-3272.5	420.0				
216	Y140	-3327.5	420.0				
217	Y141	-3382.5	420.0				
218	Y142	-3437.5	420.0				
219	Y143	-3492.5	420.0				
220	Y144	-3547.5	420.0				
221	Y145	-3602.5	420.0				
222	Y146	-3657.5	420.0				
223	Y147	-3712.5	420.0				
224	Y148	-3767.5	420.0				
225	Y149	-3822.5	420.0				
226	Y150	-3877.5	420.0				
227	Y151	-3932.5	420.0				
228	Y152	-3987.5	420.0				
229	Y153	-4042.5	420.0				
230	Y154	-4097.5	420.0				
231	Y155	-4152.5	420.0				
232	Y156	-4207.5	420.0				
233	Y157	-4262.5	420.0				
234	Y158	-4317.5	420.0				
235	Y159	-4372.5	420.0				
236	Y160	-4427.5	420.0				
237	DUMMY	-4499.5	420.0				
238	DUMMY	-4640.0	325.2				
239	V0	-4640.0	241.2				
240	V12	-4640.0	24.0				
241	V43	-4640.0	-180.4				
242	DUMMY	-4640.0	-338.4				